

Electrodynamic Wireless Power Transfer for Charging through Conductive Media

Prof. David P Arnold

Interdisciplinary Microsystems Group Dept. of Electrical and Computer Engineering University of Florida





POWERING THE NEW ENGINEER TO TRANSFORM THE FUTURE

Outline



- Wireless Power Transfer (WPT) Background
- Electrodynamic WPT (EWPT)
 - Principle and Advantages
 - Prior Works
- Miniature EWPT Receivers
 - Electrodynamic, Piezoelectric, & Dual-transduction
- Summary & Comparison



Wireless Power Transfer











Microwatts

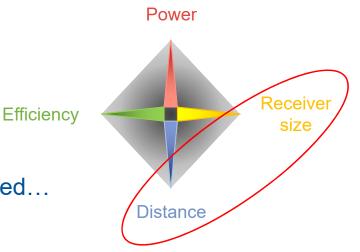
Deterministic Higher Power Density



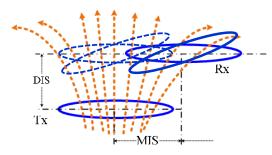
WPT Utopia



- The "Quadrilemma"
 - useful power levels
 - with relatively good efficiency
 - to compact receivers
 - over extended distances
- Once charging at a distance is obtained...
 - Safety limits / human EM exposure
 - "Cluttered" environments
 - Position & orientation independence

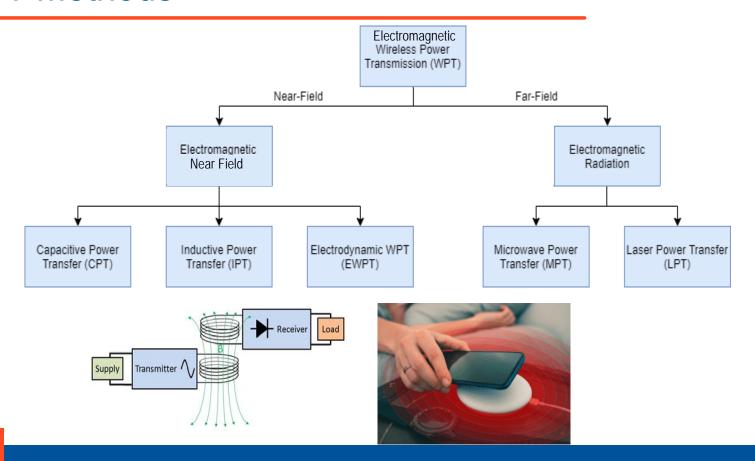






WPT Methods

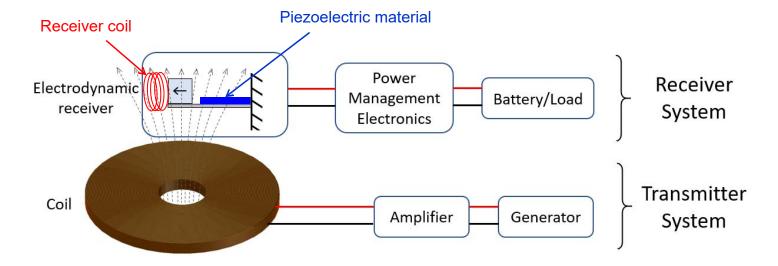




EWPT Principle



- The receiver magnet is excited by time-varying magnetic field generated by a transmitter "Electrodynamic Transduction" <--> Interaction between permanent magnet and coil
- Mechanical energy → Electrical power at receiver by one or more electromechanical transduction schemes e.g., Electrodynamic and Piezoelectric



EWPT Solves Key Problems



Inductive Coupling

EWPT

High frequency WPT (10's of kHz to 10's of MHz)

Low frequency WPT (10's to 100's of Hz)

Limited to fields \ll 1 mT_{rms} if transmitting near humans

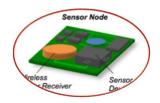
Safe to transmit fields up to 2 mT_{rms} around humans

Field **attenuated** by conductive media (metals, humans etc.) --> **heat**

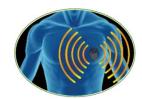
Travels virtually **unimpeded** through conductive media

Generates huge EMI

Almost **no** EMI





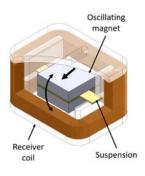


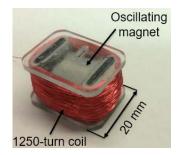


Prior Works



- Macroscale EWPT receiver
 - 13.5 cm³ prototype
 - Few volts (open-circuit) at 21 Hz





Relative independence of position and orientation (even with clutter)



Prior Works





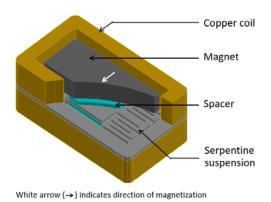
 Transmission through body using rotating magnet transmitter

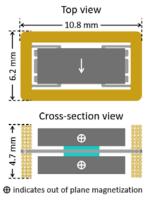


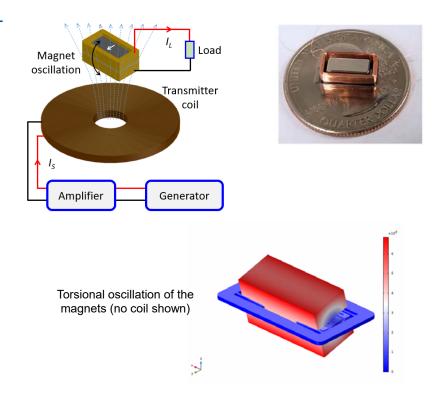
Transmission through desktop computer using coil transmitter



- Micro-fabricated electromagnetic EWPT receiver
 - Serpentine silicon suspension
 - Volume-efficient design
 - Two magnet-coil pairs
 - Torsional operation at 821 Hz



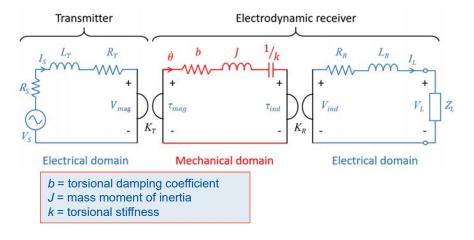








- Lumped Element Modeling (LEM)
 - Equivalent electrical circuit model



Tx electrodynamic transduction coefficient

$$K_T = \frac{ au_{mag}}{I_S} = \frac{V_{mag}}{\dot{ heta}}$$
 N.m.A-1 or V.s.rad-1

Rx electrodynamic transduction coefficient

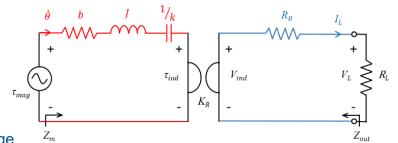
$$K_R = \frac{ au_{ind}}{I_L} = \frac{V_{ind}}{\dot{ heta}}$$
 N.m.A-1 or V.s.rad-1

Torque on the Rx magnets

$$\tau_{mag} = \left| \overrightarrow{m} \times \overrightarrow{B}_z \right| = \frac{B_r}{\mu_0} v_{mag} B_z$$



- Receiver system performance analysis using LEM
 - Simplified equivalent circuit
 - · Assumed an ideal (controlled) torque source
 - Rx coil inductance is neglected ($\omega L_R \ll R_R$)
 - Complex Z_L is replaced with resistive load R_L
 - Using standard circuit analysis, frequency-dependent load voltage

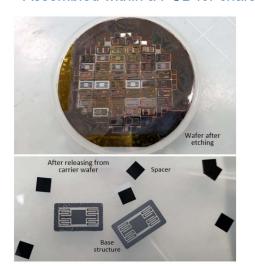


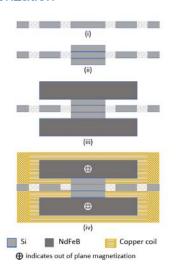
$$V_{L} = \frac{\tau_{mag} K_{R}}{\left(b + j\omega J + \frac{k}{j\omega}\right) (R_{R} + R_{L}) + K_{R}^{2}} R_{L}$$

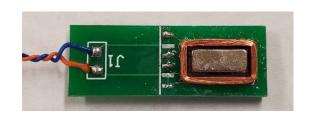
Case I: Open-circuit	Case II: Resonance	Case III: Resonance + R _{opt}	Key
$V_L\Big _{R_L=\infty} = \frac{\tau_{mag}K_R}{\left(b+j\omega J + \frac{k}{i\omega}\right)}$	$V_L \Big _{\omega = \omega_r} = \frac{\tau_{mag} K_R}{b(R_R + R_L) + K_R^2} R_L$	$V_{opt} = V_L \Big _{\substack{\omega = \omega_r \ R_L = R_L - opt}} = \underbrace{\frac{ au_{mag} K_R}{2b}}_{pa}$ pa	arameters
(~ ')ω)	$P_L\Big _{\omega=\omega_r} = \frac{V_L^2}{R_L}$	$P_{max} = P_L \Big _{\substack{\omega = \omega_r \\ R_L = R_L - opt}} = \frac{\tau_{mag}^2 K_R^2}{4b^2 R_{L - opt}}$	

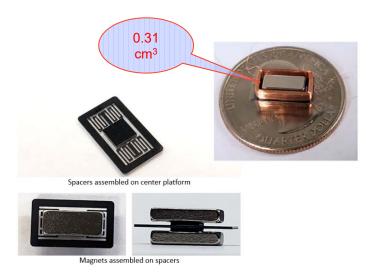


- Microfabrication of silicon suspension
- Prototype assembly
 - NdFeB magnets magnetized after assembly using pulse magnetizer
 - Assembled within a PCB for characterization





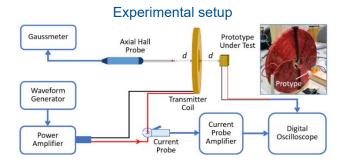


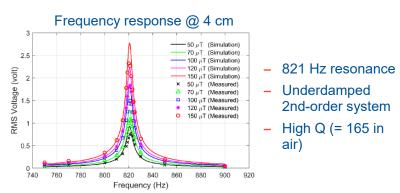




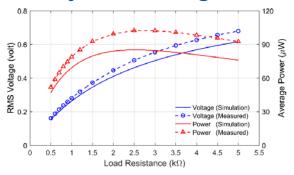


Characterization and model validation

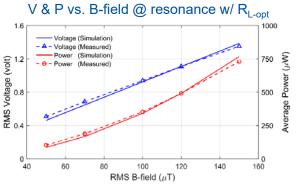








- Strong electrodynamic coupling
- Coupling strength $\gamma = 9$



- Power increases quadratically
- Nonlinearity observed from > 120 μT_{rms}



EWPT System Demo

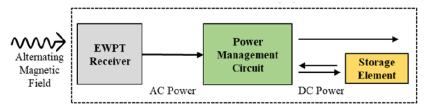


Wirelessly Rechargeable AA Battery

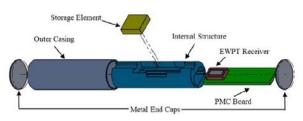




System-level integration



Exploded view of the AA battery prototype



Photographs of the system



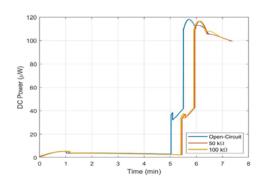


UF S. E. Smith, et al., Energies 2021

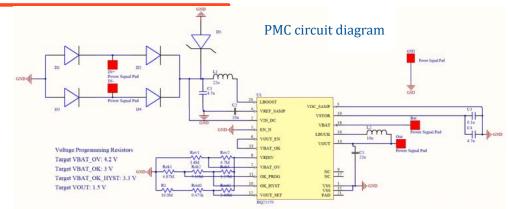
EWPT System Demo

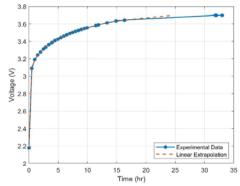


- Power Management Circuit
 - Diode Bridge Rectifier
 - TI BQ25570 energy-harvesting chip

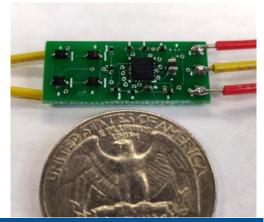


DC power across the capacitor vs time for various resistive loads





Charge cycle for the lithium polymer battery



UF

S. E. Smith, et al., Energies 2021

Piezoelectric EWPT Receiver

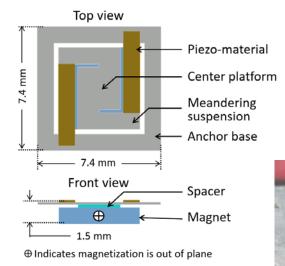


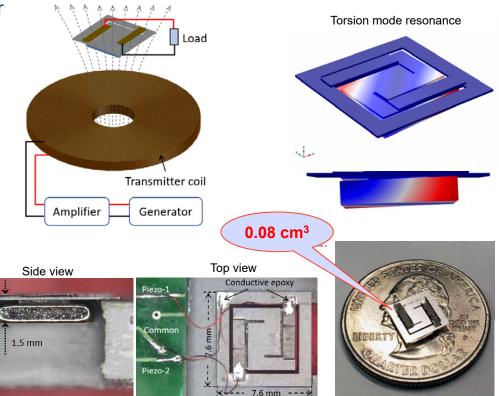
Laser micro-machined EWPT receiver

Meandering suspension

Two Piezoelectric transducers in series

Torsional operation 724 Hz

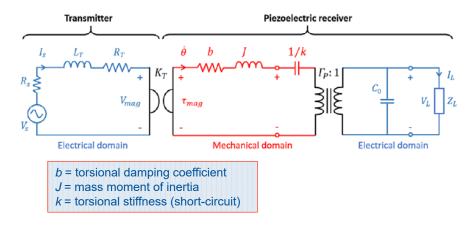




Piezoelectric EWPT Receiver



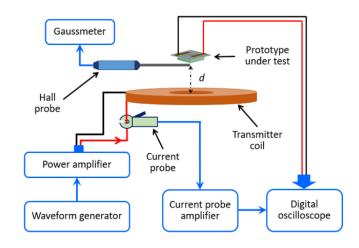
- Lumped Element Modeling (LEM)
 - Equivalent electrical circuit model



- Frequency-dependent load voltage

$$V_{L} = \frac{\Gamma_{P} \tau_{mag}}{\left(b + j\omega J + \frac{k}{j\omega}\right) (1 + j\omega C_{0} R_{L}) + \Gamma_{P}^{2} R_{L}} R_{L}$$

Experimental validation



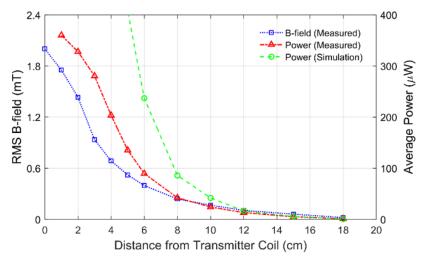


Characterization and model validation

Frequency response @ 4 cm

10 μT (Simulation) 724 Hz 70 μT (Simulation) RMS No-load Voltage (volt) × 10 μT (Measured) (Measured) 50 μT (Measured) 70 μT (Measured) 100 μT (Measured) 700 720 730 710 740 750 760 Frequency (Hz)





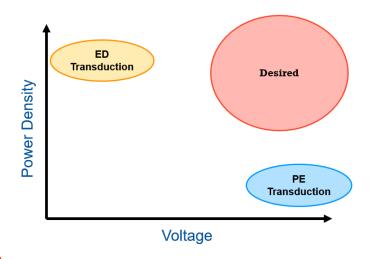


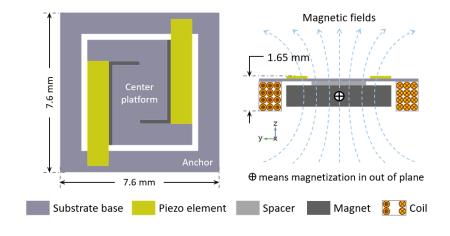
Dual-transduction EWPT Receiver



Combined with ED and PE transducers

- Two piezoelectric transducers (series connected)
- One electrodynamic transducer
- Both transducers operate simultaneously
- Torsional operation at ~ 744 Hz





Lumped Element Model (LEM)



Equivalent electrical circuit

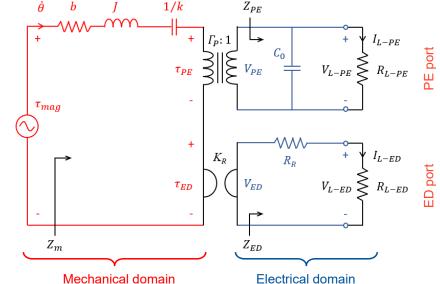
- Torque source is either a Helmholtz coil pair or multi-turn single solenoid coil
- Transformer couples the PE transducer
- Gyrator couples ED transducer

$$\tau_{mag} = \frac{B_r}{\mu_0} v_{mag} B_z \qquad k = (1 - \kappa^2) k_0$$

$$K_R = \frac{V_{ED}}{\dot{\theta}} \qquad C_0 = (1 - \kappa^2) C$$

$$\Gamma_P = \sqrt{\kappa^2 k C} \qquad \kappa^2 = 1 - (f_{r-sc}/f_{r-oc})^2$$

The voltages across corresponding load resistances



Mechanical domain

$$P_{PE} = \frac{V_{L-PE}^2}{R_{L-PE}}$$

$$P_{ED} = \frac{V_{L-ED}^2}{R_{L-ED}}$$

$$V_{L-PE} = \frac{\tau_{mag} \Gamma_P R_{L-PE}}{(1+j\omega C_0 R_{L-PE}) \left[\left(b+j\omega J + \frac{k}{j\omega} \right) + \frac{\Gamma_P^2 R_{L-PE}}{1+j\omega C_0 R_{L-PE}} + \frac{K_R^2}{R_R + R_{L-ED}} \right]}$$

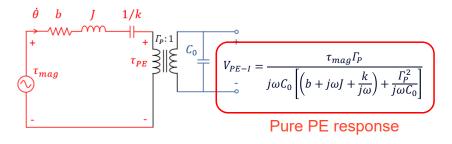
$$V_{L-ED} = \frac{\tau_{mag} K_R R_{L-ED}}{(R_R + R_{L-ED}) \left[\left(b + j\omega J + \frac{k}{j\omega} \right) + \frac{\Gamma_P^2 R_{L-PE}}{1 + j\omega C_0 R_{L-PE}} + \frac{K_R^2}{R_R + R_{L-ED}} \right]}$$

Lumped Element Model (LEM)

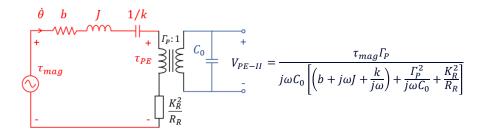


Four special cases under various harmonic excitation and load conditions

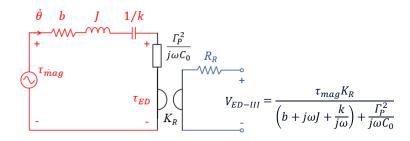
Case I: PE open-circuit with ED open



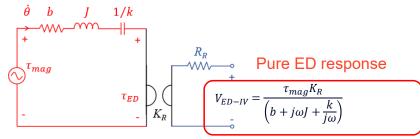
Case II: PE open-circuit with ED short



Case III: ED open-circuit with PE open



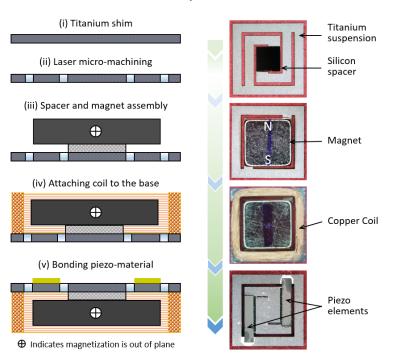
Case IV: ED open-circuit with PE short



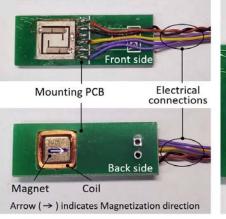
Prototype Fabrication

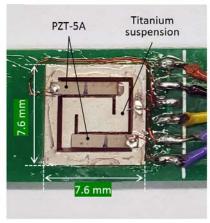


Fabrication process flow



Fabricated and assembled prototype



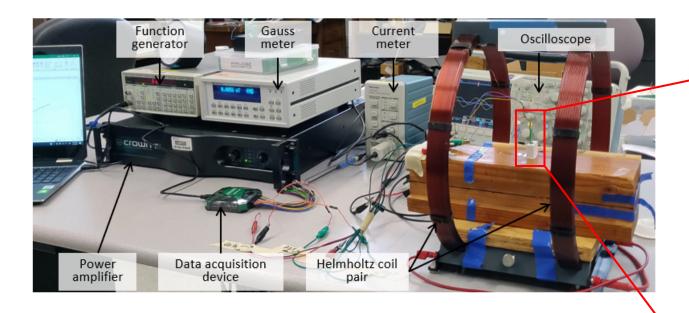


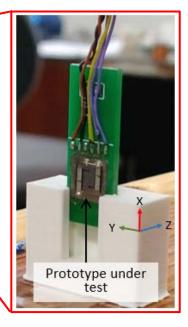
Magnet (NdFeB, N50) dimension	5 × 5 × 1 mm ³	
Piezo (PZT-5A) dimension	5 × 1 × 0.127 mm ³	
Center platform (Ti) and spacer (Si)	2.6 × 2.6 mm ²	
Suspension base (Ti) thickness	0.125 mm	
Receiver coil (Cu) inner dimension	5.6 × 5.6 × 1.4 mm ³	
Coil resistance	71 Ω	



Experimental Test Setup

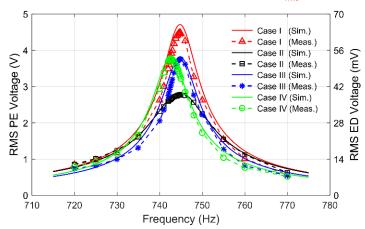






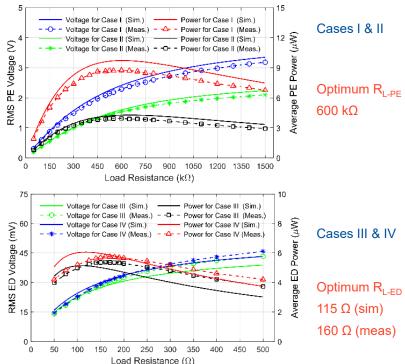






- Linear behavior with Q = 90 (in air)
- 744.8 Hz for Cases I, II & III
- No effect on resonance for ED loading condition
- 742.6 for Case IV (while PE shorted)

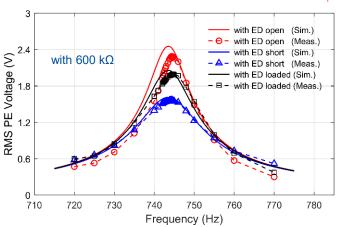
Load voltage & Power vs. load resistance @ resonance





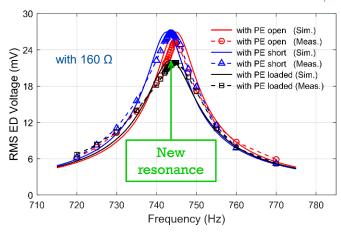






- ED loading does not affect the resonance
- However, controls the PE amplitude

ED load voltage vs. frequency @ 50 μT_{rms} w/ $R_{L-ED-opt}$

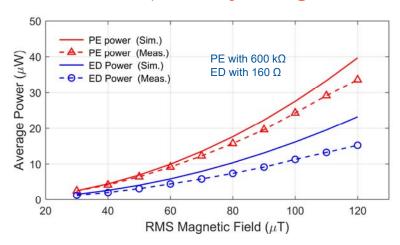


- PE loading controls the resonance
- New resonance is obtained when both transducers are at their respective R_{L-opt}



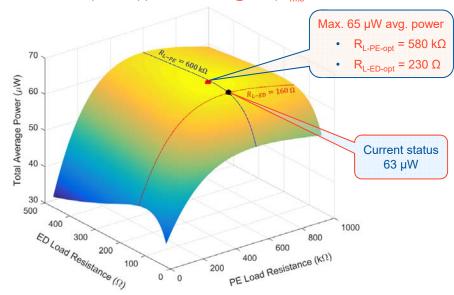


PE and ED load power vs. magnetic field @ resonance



- Power increases with magnetic fields
- Nonlinear behavior at higher fields due to
 - Spring stiffening effect
 - Nonlinear piezoelectric effect
 - Non-constant K_R

Simulated total (PE+ED) power vs. load @ 120 μT_{rms} & 743.6 Hz

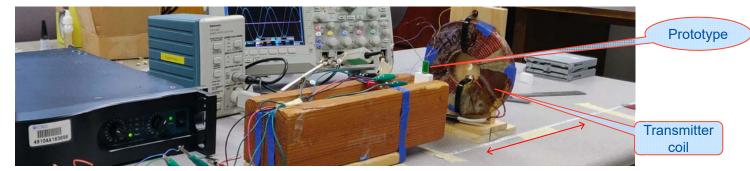


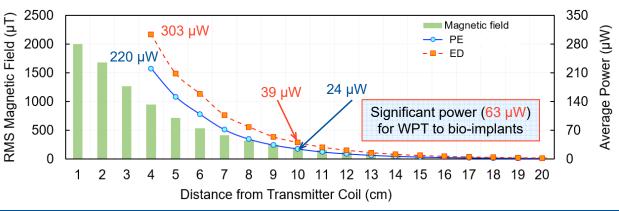
- Strongly correlated with the strength of electromechanical coupling of the transducers
- Should be carefully considered in future designs





Power vs. distance using multi-turn single solenoid coil @ resonance with R_{L-opt}







Charging through Conductive Media



Through Metal



Through Humans

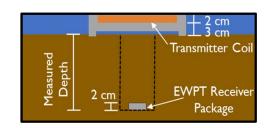


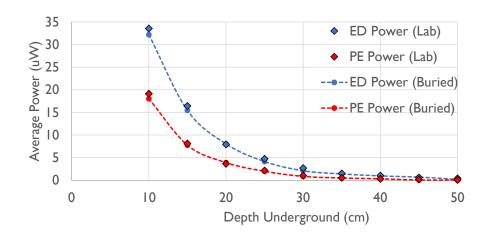
Charging through Conductive Media



Dual Transduction Receiver for Underground WPT







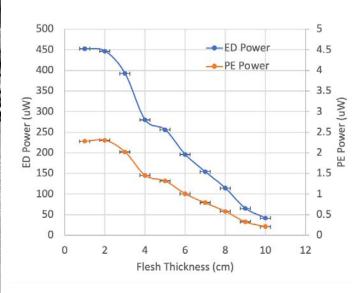
Charging through Conductive Media



Dual Transduction Receiver charging through Tissue



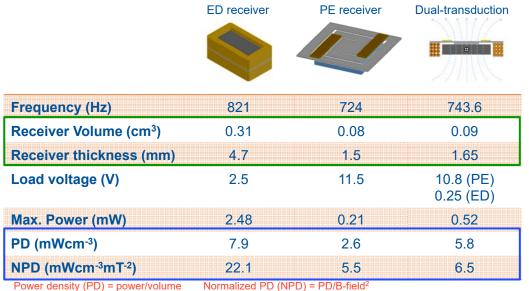


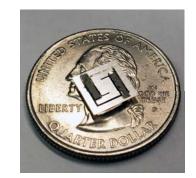


Summary & Comparison



- Designed, modeled and experimentally verified various EWPT systems
- Volume-efficient, low-profile, chip-like designs
- Application in wearables and implantable medical devices







Acknowledgements



 NSF Multi-functional Integrated System Technology (an NSF I/UCRC)



Innovating more than Moore technologies for smart systems in the Internet of Things era.

Internet of Things for Precision Agriculture (IoT4Ag)



The Internet of Things for Precision Agriculture an NSF Engineering Research Center Interdisciplinary Microsystems Group



Dr. Arnold's group

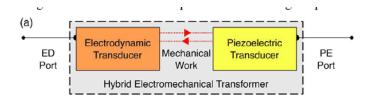






Hybrid Electromechanical Transformer





Abstract—This paper presents a hybrid electromechanical transformer that passively transfers electrical power between galvanically isolated ports by coupling electrodynamic and piezoelectric transducers. The use of these two complementary electromechanical transduction methods along with a high-Q mechanical resonance affords very large transformations of voltage at particular electrical frequencies. A chip-size is designed, simulated. fabricated prototype experimentally characterized. The 7.6 mm \times 7.6 mm \times 1.65 mm device achieves open-circuit voltage gains of 31.4 and 48.7 when operating as step-up transformer at 729.5 Hz and 1015 Hz resonance frequencies, respectively. In one operational mode, the system shows a minimum power dissipation of only 0.9 µW corresponding to a power conversion efficiency of 11.8 %. A practical application of the hybrid transformer is demonstrated through an AC-DC step-up converter. When using a 1015 Hz input signal of only 209 mV_{rms} and 2.4 mA_{rms}, the step-up converter outputs 5.3 V_{DC}

